Tinetti POMA

| Balance |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Task | Score |  |  |
| Number |  | 2 | 1 | 0 |
| 1 | Sitting Balance | 0 | 0 <br> Steady, safe | $0$ <br> Leans or slides in chair |
| 2 | Arises | 0 <br> Able without using arms | 0 <br> Able, uses arms to help | 0 <br> Unable without help |
| 3 | Attempts to Arise | O <br> Able to rise, 1 attempt | O Able, requires > 1 attempt | 0 <br> Unable without help |
| 4 | Immediate Standing First 5 sec | 0 <br> Steady without walker or other support | Steady but uses walker or other support | 0 <br> Unsteady (swaggers, moves feet, trunk sway) |
| 5 | Standing Balance | Narrow stance without support | Steady but wide stance (medial heals > 4 in apart) \& uses cane or other support | $0$ <br> Unsteady |
| 6 | Nudged <br> (subject with feet as close together as possible, examiner pushes lightly on subject's sternum with palm of hand $3 x$ ) | 0 Begins to fall | Staggers, grabs, catches self | 0 Begins to fall |
| 7 | Eyes Closed <br> (at maximum position of item 6) | 0 | Steady | 0 <br> Unsteady |
| 8 | Turing 360 Degrees | 0 | 0 Continuous steps | 0 Discontinuous steps |
| 9 | Turing 360 Degrees | 0 | Steady | 0 <br> Unsteady (grabs, staggers) |
| 10 | Sitting Down | 0 Safe, smooth motion | 0 <br> Uses arms or not a smooth motion | 0 <br> Unsafe (misjudged distance, falls into chair) |
| Column Total |  |  |  |  |
| Balance Total | /16 |  |  |  |


| Gait |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Task |  | Score |  |
| Number |  | 2 | 1 | 0 |
| 1 | Initiation of Gait immediately after told to "go" | 0 | 0 <br> No hesitancy | Any hesitancy or multiple attempts to start |
| 2 | Step Length and Height Right swing foot | 0 | 0 <br> Passes left stance foot | 0 <br> Doesn't pass left stance foot with step |
| 3 | Step Length and Height Right swing foot | 0 | Right foot completely clears floor | 0 <br> Right foot does not clear floor completely With step |
| 4 | Step Length and Height Left swing foot | 0 | $0$ <br> Passes right stance foot | Does not pass right stance foot with step |
| 5 | Step Length and Height Left swing foot | 0 | 0 <br> Left foot completely clears floor | Left foot does not clear floor completely With step |
| 6 | Step Symmetry | 0 | 0 <br> Right and left step length appear equal | 0 <br> Right and left step length not equal (estimate) |
| 7 | Step Continuity | 0 | 0 <br> Steps appear continuous | 0 <br> Stopping or discontinuity between steps |
| 8 | Path (estimated in relation to floor tiles, 12 -inch diameter; observe excursion of 1 foot over about 10 ft . of the course) | 0 <br> Straight without walking aid | Mild/ moderate deviation or uses walking aid | 0 <br> Marked deviation |
| 9 | Trunk | No sway, no flexion, no use of arms, and no Use of walking aid | 0 <br> No sway but flexion of knees or back or Spreads arms out while walking | 0 <br> Marked sway or uses walking aid |
| 10 | Walking Stance | 0 | 0 Heels almost touching while walking | 0 Heels apart |
| Column Total |  |  |  |  |
| Gait Total |  | /12 |  |  |
| Combined Balance and Gait Total = |  |  |  |  |

Tinetti: Performance Oriented Mobility Assessment. Geriatric Examination Toolkit. University of Missouri. School of Health Professions. Department of Physical Therapy. Last Updated: Jan. 2012. Accessed March 31, 2012. http://web.missouri.edu/~proste/tool/
*adapted from Berg Balance Scale Easy-Scoring System (Ahmed Y Barhameen; Roberta A Newton, 2001)

